

A random string among Poissonian obstacles

Mathew Joseph
Indian Statistical Institute Bangalore
(Joint work with Siva Athreya and Carl Mueller)

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$\mathbf{u}(t, x) \in \mathbb{R}^d$, $x \in [0, J]$, $t \in [0, T]$, with periodic boundary conditions

$$\begin{aligned}\partial_t \mathbf{u}(t, x) &= \partial_x^2 \mathbf{u}(t, x) + \dot{\mathbf{W}}(t, x), \\ \mathbf{u}(0, x) &= \mathbf{u}_0(x)\end{aligned}$$

$\dot{\mathbf{W}}$ is a vector of independent white noises: Distribution valued centred Gaussian process

$$\mathbb{E} \left(\dot{W}(h) \dot{W}(g) \right) = \int h(t, x) g(t, x) dt dx$$

Heat kernel $G : [0, T] \times [0, J] \rightarrow \mathbb{R}$

$$\partial_t G(t, x) = \frac{1}{2} \partial_x^2 G(t, x), \quad G(0, x) = \delta(x).$$

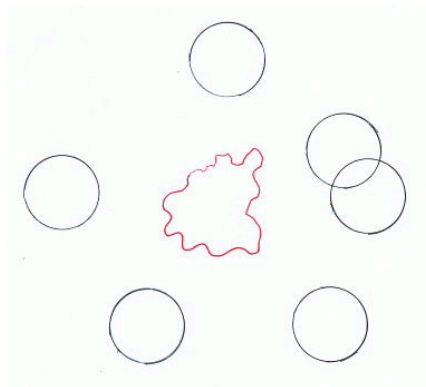
Random string solves

$$\mathbf{u}(t, x) = G_t * \mathbf{u}_0(x) + \mathbf{N}(0, t; x),$$

where $G_t * u_0(x)$ is the *deterministic* term and the *noise* term

$$\mathbf{N}(0, t; x) = \int_0^t \int_0^J G_{t-s}(x, y) \mathbf{W}(ds, dy).$$

η : Poisson point process on \mathbb{R}^d with intensity ν . (independent of string)
Closed balls of radius a around each point.



Survival: No part of the string hits any obstacle up to time T

Question: What is the probability of survival of the string?

Point process $\eta = \sum_{i \geq 1} \delta_{\xi_i}$

$H : \mathbb{R}^d \rightarrow [0, \infty]$ is a compactly supported measurable function

$$V(\mathbf{z}, \eta) = \sum_{i \geq 1} H(\mathbf{z} - \xi_i),$$

Hard obstacles: $H = \infty \cdot \mathbf{1}_{B(\mathbf{0}, a)}$

Soft obstacles: H does not take the value ∞

- Averaged Partition function

$$S_T = \mathbb{E} \left[\exp \left(- \int_0^T \int_0^J V(\mathbf{u}(s, x), \eta) dx ds \right) \right]$$

(averaging over $\dot{\mathbf{W}}$ and η)

- For hard obstacles, S_T is the probability of survival up to time T
- Averaged Path Measure

$$\mathbb{Q}_T(d\omega) = \frac{\mathbb{E}_\eta \left[\exp \left(- \int_0^t \int_0^J V(\mathbf{u}(s, x), \eta) ds dx \right) \right] \mathbb{P}_{\dot{\mathbf{W}}}(d\omega)}{S_T}.$$

(measure on path space of the string after averaging over η)

- The analogous partition function $\mathcal{S}_T = \mathbb{E} \left[\exp \left(- \int_0^T V(B_s, \eta) ds \right) \right]$
- $\mathcal{S}_T = \mathbb{E} v_\eta(t, 0)$, where

$$\begin{aligned} \partial_t v_\eta(t, x) &= \Delta v_\eta(t, x) - V(x, \eta) v_\eta(t, x) \\ v_\eta(t, 0) &= 1 \end{aligned}$$

- $v_\eta(t, 0)$ is in fact the *quenched* partition function.
- For hard obstacles, a Poissonian calculation shows

$$\mathcal{S}_T = \mathbb{E} \exp(-\nu |\chi_T(a)|),$$

where $\chi_T(a) = \cup_{0 \leq t \leq T} \mathcal{B}(B_t, a)$ is the Wiener sausage

- For hard and soft obstacles

$$\mathcal{S}_T = \exp \left(-CT^{\frac{d}{d+2}} (1 + o(1)) \right) \text{ as } T \rightarrow \infty$$

- Under the averaged measure the paths have fluctuations of order $T^{\frac{1}{d+2}}$

Theorem (Hard obstacles)

Let $d \geq 2$, $J \geq 1$ and $H = \infty \cdot \mathbf{1}_{B(0,a)}$. There are constants C_0, C_1, \dots, C_4 independent of T, J such that for $T \geq C_0 J^{2+\frac{d}{2}}$

$$C_1 \exp\left(-C_2 \left(\frac{T}{J}\right)^{\frac{d}{d+2}}\right) \leq S_T \leq C_3 \exp\left(-\frac{C_4}{1 + |\log J|} \left(\frac{T}{J^2}\right)^{\frac{d}{d+2}}\right).$$

Theorem (Soft obstacles)

Let $d \geq 2$, $J \geq 1$ and $H(x) \geq C \cdot \mathbf{1}_{B(0,a)}$. Fix $\beta > 0$. There are constants C_0, C_1, \dots, C_4 independent of T, J such that for $T \geq C_0 J^{2+\frac{d}{2}}$

$$C_1 \exp\left(-C_2 \left(\frac{T}{J}\right)^{\frac{d}{d+2}}\right) \leq S_T \leq C_3 \exp\left(-\frac{C_4}{J^{3+\beta} (1 + |\log J|)} \left(\frac{T}{J^2}\right)^{\frac{d}{d+2}}\right).$$

- The exponent of T is the same as in the case of Brownian Motion
- For hard obstacles

$$S_T = \mathbb{E} \exp \left(-\nu \left| \Gamma_T^J(a) \right| \right),$$

where $\Gamma_T^J(a) = \bigcup_{\substack{0 \leq s \leq T \\ 0 \leq x \leq J}} \mathcal{B}(\mathbf{u}(s, x), a)$

- Computing an upper bound for S_T amounts to computing lower bounds for $|\Gamma_T^J(a)|$.
- The upper bound actually holds for all $T > 0$ while the lower bound needs $T \geq C_0 J^{2+\frac{d}{2}}$.
- The constants are independent of T, J but depend on $\nu, a, \mathcal{C}, \beta$.

- In many statistical mechanics models one has a set of configurations $\omega \in \Omega$ that the physical system can take. Assume $|\Omega| < \infty$.
- Hamiltonian $H : \Omega \rightarrow \mathbb{R}$, $H(\omega)$ is the *energy* of the configuration ω
- $\mu = (\mu(\omega))_{\omega \in \Omega}$ probability distribution on Ω
- Minimizing *entropy* $\sum_{\omega} \mu(\omega) \log \mu(\omega)$ subject to *average energy* $\sum_{\omega} \mu(\omega) H(\omega) = U$ (fixed), we obtain

$$\mu_{\beta}(\omega) = \frac{e^{-\beta H(\omega)}}{\sum_{\omega} e^{-\beta H(\omega)}}, \quad (\text{Gibbs distribution})$$

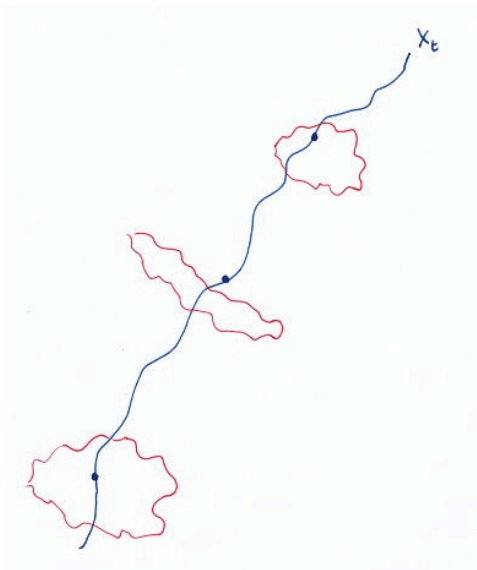
where $\beta = \beta(U)$ is the *inverse temperature*, uniquely determined by $\sum_{\omega} \mu(\omega) H(\omega) = U$.

- The *partition function* $Z(\beta) = \sum_{\omega} e^{-\beta H(\omega)}$ contains a lot of information about the model.
- Many famous discrete models: Ising Model, Directed Polymers in Random Environment, Hard Core Lattice Gas, Potts Models
- In our model the energy function is given by $\int_0^T \int_0^J V(\mathbf{u}(s, x), \boldsymbol{\eta}) dx ds$.

(Assume from now on $J = 1$)

$$\mathbf{X}_t = \int_0^1 \mathbf{u}(t, x) dx, \text{ (Center of Mass) ,}$$

$$\mathbf{R}_t = \sup_{x \in [0,1]} |\mathbf{u}(t, x) - \mathbf{X}_t|, \text{ (Radius).}$$



Lemma

(i) \mathbf{X}_t is a Brownian motion. (ii) \mathbf{X}_t and \mathbf{R}_t are independent.

$$\mathbf{u}(t, x) = G_t * \mathbf{u}_0(x) + \int_0^t \int_0^1 G_{t-s}(x, y) \mathbf{W}(ds, dy)$$

$$\mathbf{X}_t = \int_0^1 \mathbf{u}_0(x) dx + \int_0^t \mathbf{W}(dy ds)$$

$$\mathbf{u}(t, x) - \mathbf{X}_t = \int_0^1 [G(t, x - y) - 1] \mathbf{u}_0(y) dy + \int_{[0, t] \times [0, 1]} [G(t - s, x - y) - 1] \mathbf{W}(ds dy)$$

$$\text{Cov}(\mathbf{X}_t, \mathbf{u}(t, x) - \mathbf{X}_t) = \int_0^t \int_0^1 [G(t - s, x - y) - 1] dy ds = 0.$$

- Consider the event A that there is a large *obstacle-free* ball of radius $\alpha + a$ around the origin, and the string lies within this ball up to time T .

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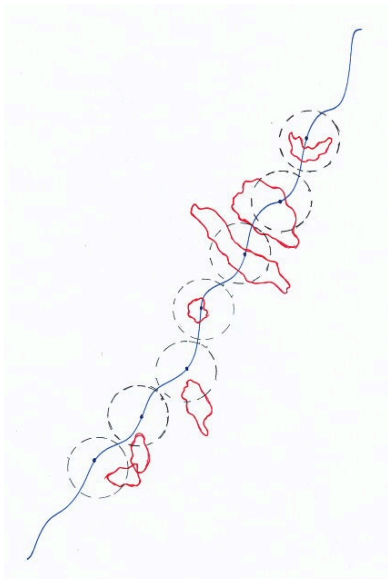
$$\begin{aligned} \mathbb{P} \left(\sup_{\substack{s \leq T \\ x \in [0,1]}} |\mathbf{u}(s, x)| \leq \frac{\alpha}{2} \right) &\geq \mathbb{P} \left(\sup_{s \leq T} |\mathbf{R}_s| \leq \frac{\alpha}{4} \right) \mathbb{P} \left(\sup_{s \leq T} |\mathbf{X}_s| \leq \frac{\alpha}{4} \right) \\ &\geq \exp \left(-C \frac{T}{\alpha^2} \right) \end{aligned}$$

(For large T the fluctuations of \mathbf{R} are *small* compared to that of \mathbf{X})

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$$\mathbb{P}(\text{no obstacles in ball of radius } \alpha + a \text{ around } \mathbf{0}) = \exp \left(-C\nu(\alpha + a)^d \right).$$

- $S_T \geq \mathbb{P}(A) \geq \exp \left(-C \frac{T}{\alpha^2} \right) \cdot \exp \left(-C\nu(\alpha + a)^d \right)$, optimize, $\alpha \approx T^{\frac{1}{d+2}}$.



- With high probability there are at least $T^{\frac{d}{d+2}}$ many time points $\tau_1 < \tau_2 < \dots \leq T$ separated by at least L (large) such that the balls of radius Λ around X_{τ_i} are disjoint.
- For large t

$$\begin{aligned} \mathbf{u}(t, \mathbf{x}) &= \int_0^1 G_t(\mathbf{x}, y) \mathbf{u}_0(y) dy + \mathbf{N}(0, t; \mathbf{x}) \\ &\approx \int_0^1 \mathbf{u}_0(y) dy + \mathbf{N}(0, t; \mathbf{x}) \\ &= \mathbf{X}_0 + \mathbf{N}(0, t; \mathbf{x}) \end{aligned}$$

- On the other hand

$$\mathbf{X}_t = \mathbf{X}_0 + \int_0^1 \mathbf{N}(0, t; y) dy$$

- For $\mathbf{f} : [0, 1] \rightarrow \mathbb{R}^d$

$$\mathcal{R}(\mathbf{f}) := \sup_{x, y \in [0, 1]} |\mathbf{f}(x) - \mathbf{f}(y)|, \quad \mathcal{S}(\mathbf{f}) := \bigcup_{x \in [0, 1]} \mathcal{B}(\mathbf{f}(x), a)$$

- For large t

$$\mathbb{P} \left(\mathcal{R}(\mathbf{N}(0, t; \cdot)) \leq \frac{\Lambda}{2}, \quad |\mathcal{S}(\mathbf{N}(0, t; \cdot))| \geq a^{d - \frac{3}{2}} \right) \geq \frac{1}{2}$$

- It is enough to show above for the spatial process

$$\begin{aligned} \mathbf{N}(0, t; \cdot) - \mathbf{N}(0, t; 0) &\stackrel{d}{=} \mathbf{N}(-t, 0; \cdot) - \mathbf{N}(-t, 0; 0) \\ &\approx \mathbf{N}(-\infty, 0; \cdot) - \mathbf{N}(-\infty, 0; 0) \end{aligned}$$

- Therefore for large t , with probability at least $\frac{1}{2}$

$$|\mathbf{u}(t, x) - \mathbf{X}_t| \leq \Lambda, \quad \text{and} \quad |\mathcal{S}(\mathbf{u}(t, \cdot))| \geq a^{d - \frac{3}{2}}. \quad (*)$$

- We count the number of times τ_i at which (*) holds.
- If the events were i.i.d. then standard large deviation theory will guarantee that with high prob. a positive fraction of the $T^{\frac{d}{d+2}}$ balls around \mathbf{X}_{τ_i} would contain *spatial* sausages of volume $a^{d-\frac{3}{2}}$ around them, all of which are disjoint.
- However these are NOT independent.
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$$\mathbf{u}(t, \cdot) = G_{t-s} * \mathbf{u}(s, \cdot) + \mathbf{N}(s, t, \cdot)$$

If $t - s$ large the first term becomes approximately constant. (see next slide)

- Recall that the τ_i are spaced L (large) apart. With high probability one can get a subsequence τ_{i_k} (of $O(T^{\frac{d}{d+2}})$ many τ_i 's) such that

$$\begin{aligned} u(\tau_{i_{k+1}}, \cdot) &= G_{\tau_{i_{k+1}} - \tau_{i_k}} * \mathbf{u}(\tau_{i_k}, \cdot) + \mathbf{N}(\tau_{i_k}, \tau_{i_{k+1}}; \cdot) \\ &\approx \int_0^1 \mathbf{u}(\tau_{i_k}, y) dy + \mathbf{N}(\tau_{i_k}, \tau_{i_{k+1}}; \cdot) \end{aligned}$$

- $\mathcal{R}(\mathbf{N}(\tau_{i_k}, \tau_{i_{k+1}}; \cdot))$ and $\mathcal{S}(\mathbf{N}(\tau_{i_k}, \tau_{i_{k+1}}; \cdot))$ are independent of the past

Lemma

For $\mathbf{f} : [0, 1] \rightarrow \mathbb{R}^d$

$$\mathcal{R}(G_t * \mathbf{f}) \leq 4de^{-4\pi^2 t} \mathcal{R}(\mathbf{f}).$$

Proof.

We consider one component f of \mathbf{f} . Let $f(x) = \sum_k a_k e^{i2\pi kx}$.

$$\begin{aligned} \sup_{x,y} |(G_t * f)(x) - (G_t * f)(y)| &= \sup_{x,y} \left| \sum_{k \neq 0} e^{-4\pi^2 k^2 t} a_k \left[e^{i2\pi kx} - e^{i2\pi ky} \right] \right| \\ &\leq 4e^{-4\pi^2 t} \left(\sum_{k \neq 0} a_k^2 \right)^{1/2} \end{aligned}$$

Since $\int_0^1 f(x) dx$ is the zeroth Fourier coefficient of f we have

$$\left(\sum_{k \neq 0} a_k^2 \right)^{1/2} = \left\| f - \int_0^1 f(x) dx \right\|_2 \leq \left\| \mathbf{f} - \int_0^1 \mathbf{f}(x) dx \right\|_2 \leq \mathcal{R}(\mathbf{f})$$

□

THANK YOU